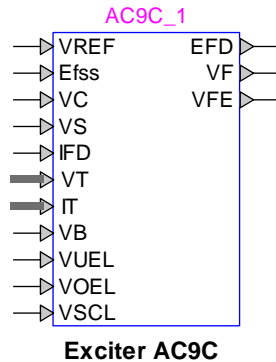


Exciters and Governors: Exciter AC9C



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1 Description

This device is an implementation of the IEEE type AC9C excitation system model. This device is implemented as described in [1]. Implementation details can be viewed by inspecting the subcircuit of this device.

1.1 Pins

This device has 14 pins:

Pin name	Type	Description	Units
VREF	Input	Reference voltage of the stator terminal voltage	pu
Efss	Input	Steady-state field voltage at $t = 0$, for initialization	pu
VC	Input	Terminal voltage of synchronous machine, transducer output	pu
VS	Input	Power System Stabilizer signal	pu
IFD	Input	Field current signal	pu
VT	Input, bundle	Terminal voltage (phasor) of synchronous machine (magnitude and phase)	pu
IT	Input, bundle	Current (phasor) of synchronous machine (magnitude and phase)	pu
VB	Input	Available exciter voltage	pu
VUEL	Input	Under Excitation Limiter signal	pu
VOEL	Input	Over Excitation Limiter signal	pu
VSCL	Input	Stator Current Limiter signal	pu
EFD	Output	Field voltage signal	pu

VF	Output	Excitation system stabilizer signal	pu
VFE	Output	Signal proportional to exciter field current	pu

1.2 Parameters

The default set of parameters can be found in [1].

1.2.1 Data tab

The parameters on the Data tab are:

1. **Gain K_{PR}** : voltage regulator proportional gain
2. **Gain K_{IR}** : voltage regulator integral gain
3. **Gain K_{DR}** : voltage regulator derivative gain
4. **Time constant T_{DR}** : lag time constant for derivative channel of PID controller
5. **Maximum regulator output V_{PIDmax}** : maximum voltage regulator output
6. **Minimum regulator output V_{PIDmin}** : minimum voltage regulator output
7. **Gain K_{PA}** : field current regulator proportional gain
8. **Gain K_{IA}** : field current regulator integral gain
9. **Maximum output V_{Amax}** : maximum current regulator output
10. **Minimum output V_{Amin}** : minimum current regulator output
11. **Gain K_A** : controlled rectifier bridge equivalent gain
12. **Time constant T_A** : controlled rectifier bridge equivalent time constant
13. **Maximum bridge output V_{Rmax}** : maximum rectifier bridge output
14. **Minimum bridge output V_{Rmin}** : minimum rectifier bridge output
15. **Gain K_F** : exciter field current feedback gain
16. **Time constant T_F** : field current feedback time constant
17. **Gain K_{FW}** : free wheel equivalent feedback gain
18. **Maximum feedback V_{FWmax}** : maximum free wheel feedback
19. **Minimum feedback V_{FWmin}** : minimum free wheel feedback
20. **Rectifier loading factor K_{C1}** : rectifier loading factor proportional to commutating reactance
21. **Rectifier loading factor K_{C2}** : rectifier loading factor proportional to commutating reactance
22. **Gain K_P** : potential circuit (voltage) gain coefficient
23. **Phase angle $\Theta_{\alpha P}$** : potential circuit phase angle (degrees)
24. **Gain K_{I1}** : compound circuit (current) gain coefficient
25. **Gain K_{I2}** : compound circuit (current) gain coefficient
26. **Reactance X_L** : reactance associated with potential source
27. **Voltage V_{B1max}** : maximum available exciter voltage
28. **Voltage V_{B2max}** : maximum available exciter voltage
29. Excitation Type option: see explanations below.
30. Power Stage Type option: see explanations below.
31. Under Excitation Limiter option: see explanations below.
32. Over Excitation Limiter option: see explanations below.
33. Stator Current Limiter option: see explanations below.

There are two possible selections for the Excitation Type option:

1. Excitation system is self-excited: VT and IT inputs must be connected.
2. Excitation system comes from a separate source: VB input must be connected

There are two possible selections for the Power Stage Type option:

1. Power Stage is chopper converter.
2. Power Stage is thyristor converter.

There are two possible selections for the Under Excitation Limiter option:

1. VUEL not available or added to the reference voltage: this option can be selected when the VUEL input signal is zero (not connected) or when it is connected and added to the reference voltage.
2. VUEL connected to the high value gate (HV gate)

There are two possible selections for the Over Excitation Limiter option:

1. VOEL not available or added to the reference voltage: this option can be selected when the VOEL input signal is zero (not connected) or when it is connected and added to the reference voltage.
2. VOEL connected to the low value gate (LV gate).

There are three possible selections for the Stator Current Limiter option:

1. VSCL not available or added to the reference voltage: this option can be selected when the VSCL input signal is zero (not connected) or when it is connected and added to the reference voltage.
2. VSCL connected to the high value gate (HV gate).
3. VSCL connected to the low value gate (LV gate).

1.2.2 Exciter tab

The parameters on the Data tab are:

1. **Rectifier loading factor K_c** : diode bridge loading factor proportional to commutating reactance
2. **Demagnetizing factor K_D** : demagnetizing factor, function of exciter alternator reactances
3. **Constant K_E** : exciter field proportional constant
4. **Time constant T_E** : exciter field time constant
5. **Minimum output limit V_{Emin}** : minimum exciter output limit
6. **Maximum field current V_{FEmax}** : maximum field current limit
7. **Voltage V_{E1}** : the exciter voltage point which is near the exciter ceiling voltage
8. **Voltage V_{E2}** : the exciter voltage point which is near 75% of V_{E1}
9. **Saturation function output $SE_{V_{E1}}$** : the exciter saturation function value at V_{E1}
10. **Saturation function output $SE_{V_{E2}}$** : the exciter saturation function value at V_{E2}

The exciter saturation function is defined as

$$S_E = A_{EX} e^{B_{EX} E_{FD}} \quad (1)$$

which gives the approximation saturation for any E_{FD} (exciter output voltage). According to [2] (see pages 562 and 563), the coefficients A_{EX} and B_{EX} can be found from:

$$A_{EX} = \frac{S_{V_{E2}}^4}{S_{V_{E1}}^3} \quad (2)$$

$$B_{EX} = \frac{4}{V_{E1}} \ln \left(\frac{S_{V_{E1}}}{S_{V_{E2}}} \right) \quad (3)$$

In the literature [2] $V_{E1} = V_{E_{max}}$ and $V_{E2} = V_{E_{0.75max}}$.

2 Initial conditions

The reference voltage V_{REF} can be manually or automatically set by connecting or not connecting the input signal V_{REF} , respectively. When V_{REF} is not connected (the signal is zero), the reference voltage is internally found from the steady-state solution. When V_{REF} is connected, its initial value must match the per unit steady-state voltage of the stator terminal voltage, since otherwise the generator voltage will not start at the actual steady-state.

3 References

- [1] "IEEE Recommended Practice for Excitation System Models for Power System Models for Power System Stability Studies," IEEE Standard 421.5-2016.
- [2] P. M. Anderson and A. A. Fouad, "Power system control and stability", second edition, IEEE Press, Wiley Interscience, 2003.