

# Exciters and Governors: Governor-Turbine IEESGO



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## 1 Description

This device is an implementation of a general model for steam turbine and governor IEESGO. This device is implemented as described in [1]. Implementation details can be viewed by inspecting the subcircuit of this device.

### 1.1 Pins

This device has 3 pins:

Pin name	Type	Description	Units
Pm_ic	Input	Steady-state mechanical power at t = 0, for initialization	pu
w	Input	Mechanical speed	pu
Pm	Output	Turbine mechanical power	pu

### 1.2 Parameters

The default set of parameters are obtained from [2].

#### 1.2.1 Governor tab

The parameters on the Data tab are:

1. **Governor gain  $K_1$** : Governor gain
2. **Lag time constant  $T_1$** : governor lag time constant
3. **Lead time constant  $T_2$** : governor lead time constant
4. **Lag time constant  $T_3$** : governor lag time constant
5. **Maximum power limit  $P_{MAX}$** : maximum power limit
6. **Minimum power limit  $P_{MIN}$** : minimum power limit

## 1.2.2 Turbine tab

The turbine tab allows to input:

1. **Time constant  $T_4$** : steam flow time constant
2. **Time constant  $T_5$** : reheater time constant
3. **Time constant  $T_6$** : IP-LP reheater time constant
4. **Reheater fraction of shaft power  $K_2$** : reheater fraction of power shaft
5. **IP-LP fraction of shaft power  $K_3$** : IP-LP power fraction

## 2 Initial conditions

The initial output is equal to the generator mechanical power (base for power) at  $t = 0$  s.

## 3 References

- [1] "Dynamic Models for Turbine-Governors in Power System Studies," Technical report PES-TR1. IEEE Power & Energy Society Jan 2013.
- [2] P. Kundur, "Power System Stability and Control", McGraw-Hill 1994