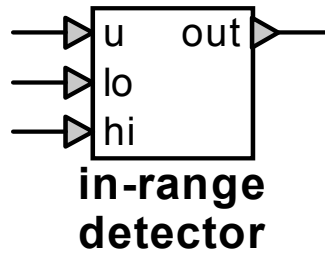


# Control function: in-range detector



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## 1 Description

This device indicates when the value of a signal lies within a defined interval. The output value is 1 when  $lo \leq u < hi$ , and is 0 otherwise.

### 1.1 Pins

This device has four pins:

<i>pin</i>	<i>type</i>	<i>description</i>
u	input	measured input
lo	input	range low boundary
hi	input	range high boundary
out	output	detector output

### 1.2 Parameters

The following parameter must be defined:

<i>parameter</i>	<i>description</i>	<i>units</i>
stepped	=1 to indicate stepped transitions =0 to indicate ramped transitions	

The value of the parameter *stepped* determines whether the device operates with *stepped* or *ramped* transitions. In *stepped* mode (the default for ideal logical signals), the output is represented as a stepped signal, where changes in value are observed as vertical steps at the time they occur. In *ramped* mode, the value transitions of the output are seen as ramps between  $t-\Delta t$  and  $t$ .

### 1.3 Input

The input pins may be connected to any control signal.

### 1.4 Output

The output has the value 1 or 0 indicating the result of the in-range detection. When the input signal  $u(t)$  lies inside the range defined by the boundary values  $lo(t)$  and  $hi(t)$ , the output is 1, otherwise it is 0.

The representation of the output as having *stepped* or *ramped* transitions is determined by the value given to the parameter *stepped*.

### 1.5 Representation

The implementation of the model can be inspected by opening the device's subcircuit.

The model applies the following equation:

$$\begin{array}{ll} \text{when } lo(t) \leq u(t) < hi(t) & \text{output} = 1 \\ \text{otherwise} & \text{output} = 0 \end{array} \quad (1)$$