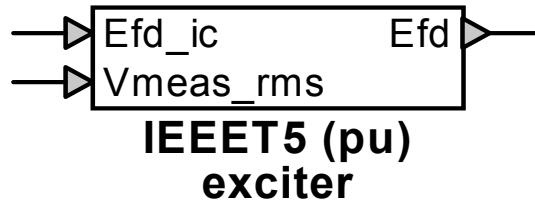


# Machine control : exciter IEEEET5 pu



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## 1 Description

This device is an implementation of an IEEE Type 5 exciter similar to PSS/E's IEEEET5 exciter model. This version of the exciter interprets all input and output values as per-unit quantities. For a version with input and output in physical units, use the device "exciter IEEEET5".

### 1.1 Pins

This device has three pins:

<i>pin</i>	<i>type</i>	<i>description</i>	<i>units</i>
Efd_ic	input pin	initial field voltage at t=0	pu(Efd_base)
Vmeas_rms	input pin	measured rms voltage	pu(V_base)
Efd	output pin	field voltage	pu(Efd_base)

### 1.2 Parameters

The value of the following parameters must be defined:

<i>parameter</i>	<i>description</i>	<i>units</i>
Trh	1/gain of regulator	s
Te	time constant of exciter	s
Ke	gain of exciter	
Kv	regulator zone	pu(V_base)
Vrmin	regulator low limit	pu(Efd_base)
Vrmax	regulator high limit	pu(Efd_base)
E1	E value of point 1 of saturation curve	pu(Efd_base)
S1	S value of point 1 of saturation curve	pu(Efd_base)
E2	E value of point 2 of saturation curve	pu(Efd_base)

(includes base conversion)

S2	S value of point 2 of saturation curve	pu(Efd_base)
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### 1.3 Input

The input pins may be connected to any control signals.

The following inputs are available:

input	description	units
Efd_ic	initial field voltage at t=0	pu(Efd_base)
Vmeas_rms	measured rms voltage	pu(V_base)

### 1.4 Output

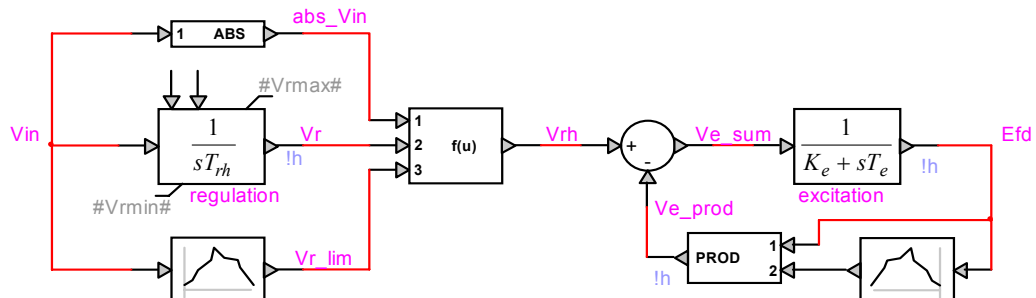
The output value is the calculated field voltage, in per-unit of the base field voltage.

output	description	units
Efd	field voltage	pu(Efd_base)

### 1.5 Representation

The implementation of the model can be inspected by opening the device's subcircuit. The model is self-initializing at t=0.

The dynamic representation of the model is the following:



where

$$V_{in} = V_{ref} - V_{meas\_rms} \quad (1)$$

$$\begin{aligned} V_{r\_lim} &= V_{r\_min} && \text{when } V_{in} < -K_v \\ &= V_{r\_max} && \text{when } V_{in} > K_v \\ &= 0 && \text{when } -K_v \leq V_{in} \leq K_v \end{aligned} \quad (2)$$

$$\begin{aligned} V_{rh} &= V_r && \text{when } |V_{in}| \leq K_v \\ &= V_{r\_lim} && \text{when } |V_{in}| > K_v \end{aligned} \quad (3)$$

with the value of  $V_{ref}$  calculated to produce  $E_{fd} = E_{fd\_ic}$  at t=0 .

The internal signals are:

<i>signal</i>	<i>description</i>	<i>units</i>
Vin	control input	pu(V_base)
Vr	regulator voltage	pu(Efd_base)
Vr_lim	regulator limit	pu(Efd_base)
Vrh	actual regulator voltage	pu(Efd_base)