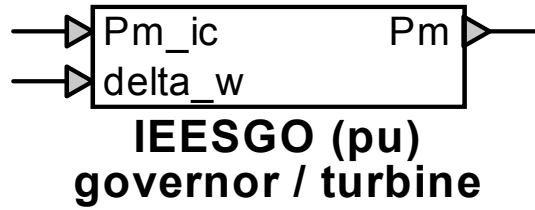


Machine control : governor/turbine IEESGO pu



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1 Description

This device is an implementation of an IEEE standard turbine and governor system similar to PSS/E's IEESGO turbine/governor model. This version of the model interprets all input and output values as per-unit quantities. For a version with input and output in physical units, use the device "turbine/governor IEESGO".

1.1 Pins

This device has three pins:

| <i>pin</i> | <i>type</i> | <i>description</i> | <i>units</i> |
|------------|-------------|-------------------------|----------------|
| Pm_ic | input pin | mechanical power at t=0 | pu(S_base) |
| delta_w | input pin | speed deviation | pu(omega_base) |
| Pm | output pin | mechanical power | pu(S_base) |

1.2 Parameters

The value of the following parameters must be defined:

| <i>parameter</i> | <i>description</i> | <i>units</i> |
|------------------|------------------------------------|--------------|
| K1 | controller gain | |
| K2 | reheater fraction | |
| K3 | IP-LP fraction | |
| T1 | time constant (lag) of controller | s |
| T2 | time constant (lead) of controller | s |
| T3 | time constant (lag) of governor | s |
| T4 | time constant (lag) of steam inlet | s |
| T5 | time constant (lag) of reheater | s |

| | | |
|------|------------------------------|------------|
| T6 | time constant (lag) of IP-LP | s |
| Pmin | minimum power order | pu(S_base) |
| Pmax | maximum power order | pu(S_base) |

1.3 Input

The input pins may be connected to any control signals.

The following inputs are available:

| <i>input</i> | <i>description</i> | <i>units</i> |
|--------------|-------------------------|----------------|
| Pm_ic | mechanical power at t=0 | pu(S_base) |
| delta_w | speed deviation | pu(omega_base) |

1.4 Output

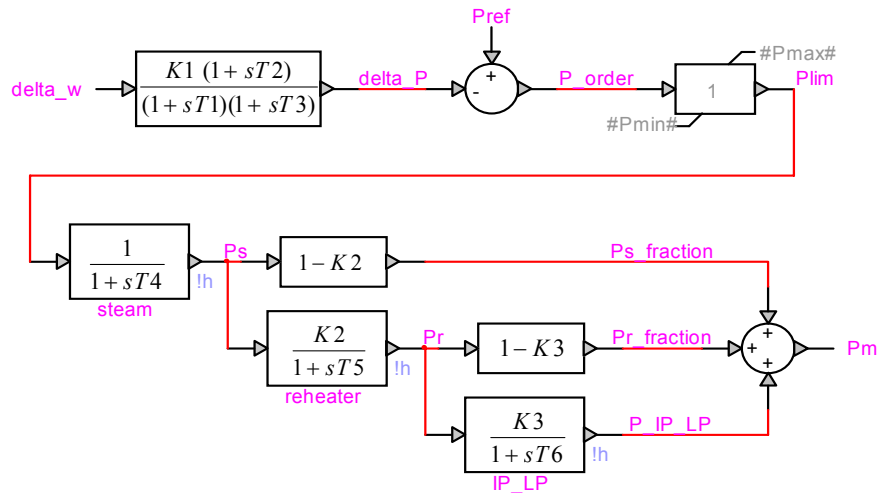
The output value is the calculated mechanical power, in per-unit of the machine base power.

| <i>output</i> | <i>description</i> | <i>units</i> |
|---------------|--------------------|--------------|
| Pm | mechanical power | pu(S_base) |

1.5 Representation

The implementation of the model can be inspected by opening the device's subcircuit. The model is self-initializing at t=0.

The dynamic representation of the model is the following:



with the value of P_{ref} calculated to produce $P_m = P_{m_ic}$ at t=0 .

The internal signals are:

| <i>signal</i> | <i>description</i> | <i>units</i> |
|---------------|----------------------------|--------------|
| delta_P | mechanical power deviation | pu(S_base) |

| | | |
|-------------|-----------------------------|------------|
| P_order | power order | pu(S_base) |
| Plim | limiter power order | pu(S_base) |
| Ps | steam power order | pu(S_base) |
| Ps_fraction | steam power contribution | pu(S_base) |
| Pr | reheater power order | pu(S_base) |
| Pr_fraction | reheater power contribution | pu(S_base) |
| P_IP_LP | IP-LP power contribution | pu(S_base) |