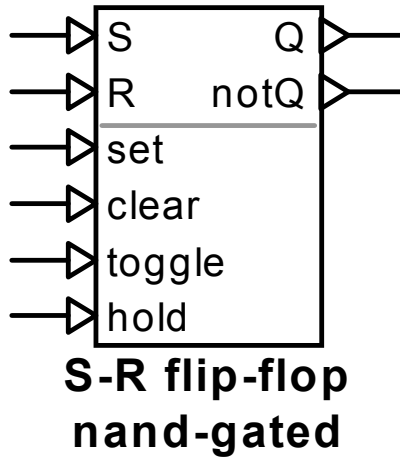


# Flip-flop: S-R nand-gated unclocked full-override



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## 1 Description

This device is an implementation of a nand-gated unclocked S-R flip-flop with full override controls. For a simple version without the override controls, use the device "S-R nand-gated unclocked".

### 1.1 Pins

This device has eight pins:

<i>pin</i>	<i>type</i>	<i>description</i>
S	input	S input
R	input	R input
set	input	set override
clear	input	clear override
toggle	input	toggle override
hold	input	hold override
Q	output	Q output
notQ	output	notQ output

### 1.2 Parameters

The initial value of  $Q$  must be defined if the device is possibly holding or toggling at  $t=0$ . When the device operates in clearing or setting mode at  $t=0$ , the initial value is ignored.

The value of the *stepped\_mode* flag determines whether the device operates in *stepped* or *ramped* mode. In *stepped* mode (the default for ideal logical signals), the outputs are represented as stepped signals, where changes in value are observed as vertical steps at the time they occur. In *ramped* mode, the value transitions of the outputs are seen as ramps between  $t-\Delta t$  and  $t$ .

<i>parameter</i>	<i>description</i>
Q_ini	initial value of Q if holding or toggling at $t=0$
stepped_mode	=1 to indicate stepped mode (default) =0 to indicate ramped mode

### 1.3 Input

The input pins may be connected to any control signals.

Numerical input values are automatically interpreted as logical values by this device, as follows:

<i>input</i>	<i>converted logical value</i>	<i>logical value representation</i>
value > 0	true	1
value ≤ 0	false	0

### 1.4 Output

The outputs are  $Q$  and its logical inverse *notQ*. Their representation as *stepped* or *ramped* signals is determined by the value given to the parameter *stepped\_mode*.

The numerical representation of the output logical values is:

<i>output logical value</i>	<i>output numerical value</i>
true	1
false	0

### 1.5 Representation

The implementation of the model can be inspected by opening the device's subcircuit.

The model applies the following logic for determining its state:

<i>rule sequence</i>	<i>action</i>	<i>output</i>
if set>0	setting	$Q(t) = 1$
else if clear>0	clearing	$Q(t) = 0$
else if toggle>0	toggling	$Q(t) = \text{not } Q(t-\Delta t)$
else if hold>0	holding	$Q(t) = Q(t-\Delta t)$
else if S>0 and R>0	setting	$Q(t) = 1$
else if S≤0 and R≤0	holding	$Q(t) = Q(t-\Delta t)$
else if S>0	setting	$Q(t) = 1$
else if S≤0	clearing	$Q(t) = 0$
endif		
if holding at $t=0$	use Q_ini	$Q(0) = Q\_ini$
if toggling at $t=0$	use Q_ini	$Q(0) = Q\_ini$

