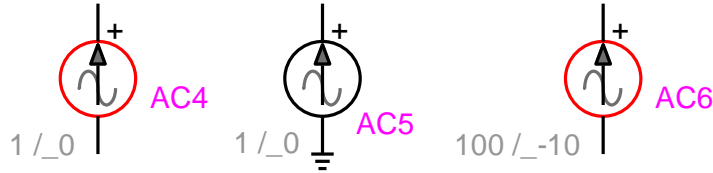


# AC current source device



AC current source device.....	1
1 Available versions.....	1
1.1 When changing phases.....	1
1.2 Default color coding.....	1
1.3 The generic version of “I ac”.....	1
1.3.1 Parameters.....	1
1.3.2 Netlist format.....	2
2 Steady-state model.....	3
3 Frequency Scan model.....	3
4 Time-domain model.....	3

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## 1 Available versions

The “I ac” device accepts both 1-phase (general) and 3-phase signals. The 3-phase version provides 3 sources with phase shift. The default phase shift constitutes a positive sequence source.

### 1.1 When changing phases

- ❑ When the device is in its 1-phase state and any of its signals are changed to 3-phase, but the device is not double-clicked, balanced positive sequence conditions are assumed using the amplitude and the phase angle of phase-A. The user can double-click and modify the sources as required. The Netlist is generated for the 3-phase version.
- ❑ When the device is in its 3-phase state and its signal is changed to 1-phase, but the device is not double-clicked, phase-A quantities are automatically retained for the 1-phase version. The Netlist is generated for the 1-phase version.

### 1.2 Default color coding

The default color coding changes the device line color to red to indicate that the source is active in steady-state. The source is active in steady-state when its start time is smaller than 0.

### 1.3 The generic version of “I ac”

#### 1.3.1 Parameters

The generic version of “I ac” has two pins. The generic version of “I ac” allows entering all required parameters for a cosine waveform:

$$i(t) = I_m \cos(\omega t + \theta)$$

$$\omega = 2\pi f$$

A typical example for  $I_m = 10A$ ,  $t_{start} = 5ms$  and  $t_{stop} = 20ms$  is shown in Figure 1. The waveform precision is related to the simulation time-step  $\Delta t$ .

- $I_m$  amplitude of the cosine waveform, any value, default units are A.
- $f$  frequency in Hertz, must be greater than 0.
- $\theta$  phase angle, default units are degrees.
- $t_{start}$  start time, if  $t < t_{start}$  the source is an open-circuit. If  $t_{start} < 0$ , the source is active in the steady-state solution.
- $t_{stop}$  stop time, if  $t > t_{stop}$  the source is an open-circuit. The stop time must be greater than the start time.

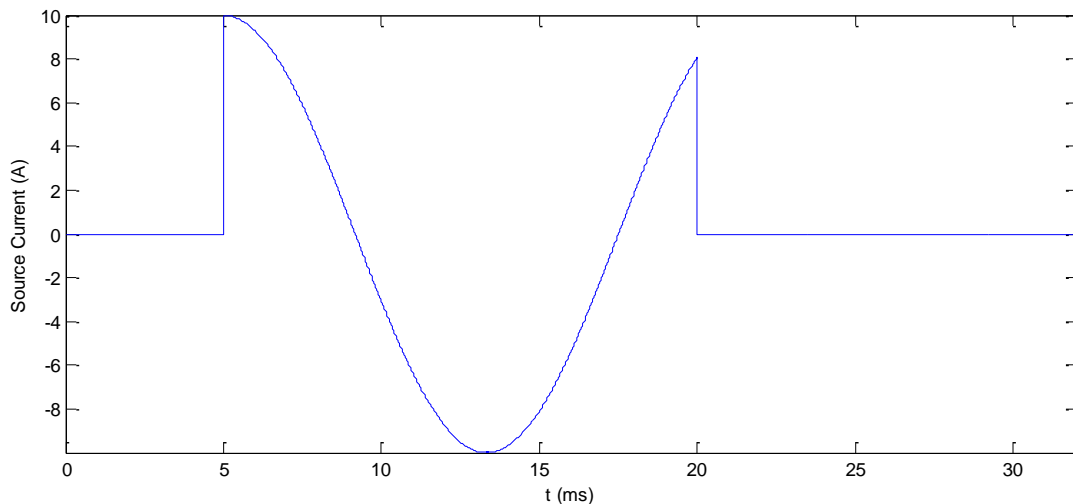


Figure 1 Sample source waveform for  $t_{start} = 5ms$  and  $t_{stop} = 20ms$

### 1.3.2 Netlist format

```
_Isine;AC1;2;2;s1,s2,
10,60,0,-1,1E15,?v,?i,?p,
```

Field	Description
<code>_Vsine</code>	Part name
<code>AC1</code>	Instance name, any name.
<code>2</code>	Total number of pins
<code>2</code>	Number of pins given in this data section
<code>s1</code>	Signal name connected to k-pin (positive), any name
<code>s2</code>	Signal name connected to m-pin, any name
<code><math>I_m</math></code>	Amplitude
<code><math>f</math></code>	frequency, default is 60
<code><math>\theta</math></code>	Phase angle
<code><math>t_{start}</math></code>	Start time
<code><math>t_{stop}</math></code>	Stop time
<code>?v</code>	Request for voltage scope, sent to scope group vb (branch voltages), optional
<code>?i</code>	Request for current scope, sent to scope group ib (branch currents), optional
<code>?p</code>	Request for power scope, sent to scope group p (branch power), optional

Source data fields are saved in ParamsA, ParamsB and ParamsC device attributes.

The m-pin of this device can be deleted to create an automatic ground connection.

If there is only one pin, the second signal name field is not present.

A 3-phase version example of a source that is active in steady-state and never stops:

```
_Isine;AC1a;2;2;s12a,s13a,  
10,60,0,-1,1E15,  
_Isine;AC1b;2;2;s12b,s13b,  
10,60,-120,-1,1E15,  
_Isine;AC1c;2;2;s12c,s13c,  
10,60,120,-1,1E15,
```

EMTPWorks automatically generates 3 separate sources, one per phase. The phase identification character (a, b or c) is automatically appended to the device instance name and signals.

When a source phase is changed, but the source is not double-clicked, the Netlist generator places a code <b> to indicate to EMTP that the source is balanced and the phase angle for phases B and C must be automatically calculated from phase A for a positive sequence source.

```
_Isine;AC1a;2;2;s12a,s13a,  
10,60,0,-1,1E15,  
_Isine;AC1b;2;2;s12b,s13b,  
<b>,,,,,  
_Isine;AC1c;2;2;s12c,s13c,  
<b>,,,,,
```

## 2 Steady-state model

The “I ac” device is represented in steady-state for automatic harmonic initialization. The harmonic initialization process must solve the network for all available source frequencies. The steady-state phasor value of a given source is only evaluated if the source frequency is equal to the solved frequency and  $t_{\text{start}} < 0 < t_{\text{stop}}$ . The source is an open-circuit otherwise. This phasor is *independent* from the source frequency and is evaluated as:

$$i_{\text{ss}} = I_m (\cos \theta + j \sin \theta) \quad (1)$$

## 3 Frequency Scan model

The source automatically participates at each scan frequency according to equation (1). The source frequency is set to the scanned frequency. The source participates only if  $t_{\text{start}} < 0 < t_{\text{stop}}$ , it is an open-circuit otherwise.

## 4 Time-domain model

The device is evaluated at each simulation time-point according to the equation:

$$i(t) = I_m \cos(\omega(t - t_{\text{start}}) + \theta) \quad \text{for } t \geq t_{\text{start}} \quad (2)$$

The source is active (not an open-circuit) for  $t_{\text{start}} \leq t \leq t_{\text{stop}}$ .