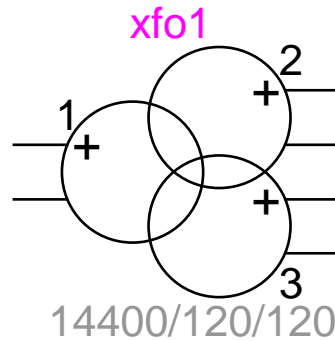


Single-phase 3-winding transformer



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1 Introduction

This device is a single-phase 3-winding transformer model including the winding impedances and the magnetization branch.

The magnetization branch is composed of a resistance in parallel with a non-linear inductance. If hysteresis is simulated, the non-linear inductance is replaced by a hysteresis reactor. The non-linear behavior of the magnetization branch can be defined with different data types:

- the current-flux points of the non-linear inductance
- the current-voltage points of the excitation test report
- the magnetic field-induction points of the material

Initial flux conditions can be specified in order to simulate a residual flux at the beginning of the simulation.

2 Parameters

- ❑ **Nominal frequency:** Frequency of application for this device (surrounding network frequency). Used when the inductance values are specified in Ohms and for the calculation of the flux points for the magnetization branch
- ❑ **Winding 1 voltage:** Winding 1 nominal voltage in RMS line-to-line
- ❑ **Winding 2 voltage:** Winding 2 nominal voltage in RMS line-to-line
- ❑ **Winding 3 voltage:** Winding 3 nominal voltage in RMS line-to-line
- ❑ **Nominal power:** Nominal power of the transformer. Used as a base when parameters are defined in per unit.
- ❑ **Winding R_{ij} :** short-circuit resistance between windings i and j seen from the winding i . Displayed only if the resistances unit is pu .
- ❑ **Winding X_{ij} :** short-circuit inductance between windings i and j seen from the winding i . Displayed only if the inductances unit is pu .

- Winding i R:** resistance of the winding i . Displayed only if the inductances unit is not pu .
- Winding i X:** inductance of the winding i . Displayed only if the inductances unit is not pu .
- Magnetization curve definition:** select the type of data and the units used to define the magnetization reactance.
 - If Current-Voltage is selected, the excitation test data points are entered in the table.
 - If Current-Flux is selected, the magnetization non-linear inductance current-flux data points are entered.
 - If *Magnetic Field-Induction* is selected, the magnetic material H-B curve data points are entered. In that case, **the saturation point current and flux** must be entered. The saturation point is the point on the H-B curve where the upward and downward branches of the major hysteresis loop meets for positive value of H.
 - If **Add Air-core inductance segment** is checked, the last point of the characteristic corresponds to the positive saturation point, else it is a point before the last. In it is not checked, the air-core inductance is defined by the slope of the last entered segment.
- The characteristic entered must be monotonically increasing.
- Saturation point current:** current corresponding to the saturation point. Only when *Magnetic Field-Induction* input type is selected. If **Add air-core inductance segment** is checked, it corresponds to the last point of the H-B table, else, it is point n-1.
- Saturation point flux:** flux corresponding to the saturation point. Only when *Magnetic Field-Induction* input type is selected. If **Add air-core inductance segment** is checked, it corresponds to the last point of the H-B table, else, it is point n-1.
- Add air-core inductance segment:** Add an extra segment to the characteristic entered in the table. This segment corresponds to the air-core reactance inductance.
- L_{sat}:** Air-core reactance value.
- Magnetization resistance/losses:**
 - If the unit is set to ohm, this is the resistance in parallel with the nonlinear inductance of the transformer magnetization branch.
 - If the unit is set to kW, this is the losses for 1pu of voltage during the excitation test. The resistance is calculated using the loss value.
- Simulate hysteresis loops:** include the hysteresis reactor of the magnetization branch and exclude the non-linear inductance. If this box is checked, the full upward (lower) branch of the major hysteresis loop must be entered in the table. The negative abscise points must be entered.
 - If hysteresis are simulated, the following constraints apply to the non-linear characteristic data:
 - the negative saturation point should not be entered.
 - the first point entered must have lower magnitude of current and flux than the positive saturation point, else it is discarded. If **Add air-core inductance segment** is checked, the positive saturation point is the last point entered in the non-linear characteristic magnetization data table. If it is not checked, the positive saturation point is the one before the last in the table.
 - At least 3 points must be entered
 - The segment slopes cannot be zero.
- Exclude magnetization branch model:** Exclude the magnetization branch of the model.

The initial flux conditions are entered on the second data tab (IC):

- Initial flux (ϕ_0):** residual flux of the transformer at the beginning of the simulation.

When resistances and inductances units are pu, then the conversion is:

$$R1 = \frac{1}{2}(R12 + R13 - R23) \quad (1)$$

$$X1 = \frac{1}{2}(X12 + X13 - X23) \quad (2)$$

$$R2 = \frac{1}{2}(R12 - R13 + R23) \quad (3)$$

$$X2 = \frac{1}{2}(X12 - X13 + X23) \quad (4)$$

$$R3 = \frac{1}{2}(-R12 + R13 + R23) \quad (5)$$

$$X3 = \frac{1}{2}(-X12 + X13 + X23) \quad (6)$$

Where R_i, X_i are respectively the resistance and inductance of winding i , R_{ij}, X_{ij} are the short-circuit resistance and inductance between winding i and j seen from the winding i .

3 Steady-state model

Steady-state representation based on subnetwork contents.

4 Initial conditions

Automatic initial conditions are found from the steady-state solution. Manual initial conditions can be provided for individual transformer phase unit fluxes.

5 Frequency Scan model

Steady-state representation based on subnetwork (power) contents for each frequency.

6 Time-domain model

Time-domain representation based on subnetwork contents.